

# High resolution seismic imaging

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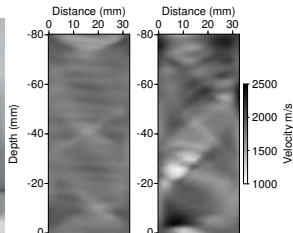
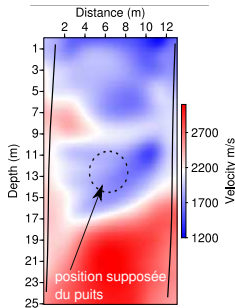
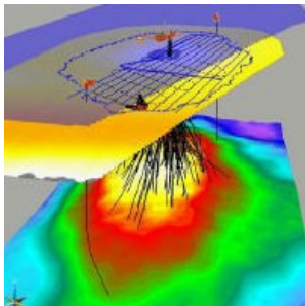
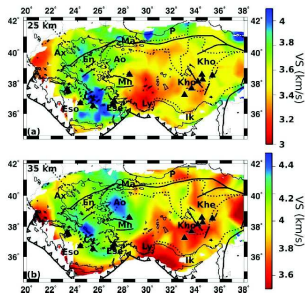
# Outline

- 1 Introduction
- 2 Algorithm
- 3 Example on the Valhall Oil & Gas field
- 4 Perspectives and challenges on the HPC side

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# Multi-scale challenges of geophysical imaging



# Seismic imaging of the Earth

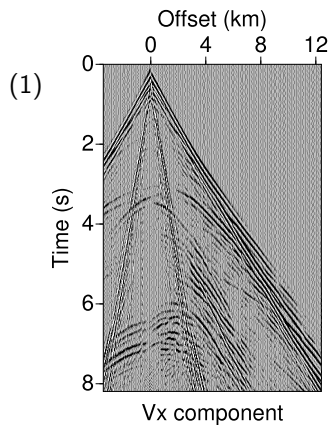
- Imaging/tomography : reconstruction of Earth subsurface properties from indirect measurements of seismic waves

$$\frac{\partial U}{\partial t} + \Lambda \frac{\partial U}{\partial x_i} = F_0 \quad (1)$$

# Seismic imaging of the Earth

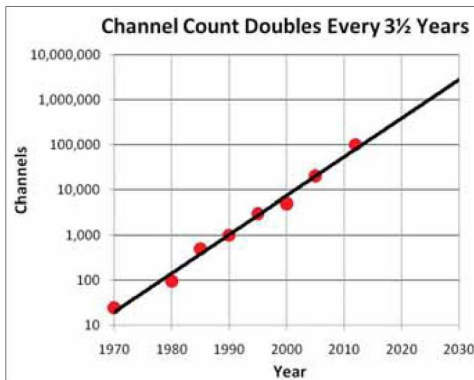
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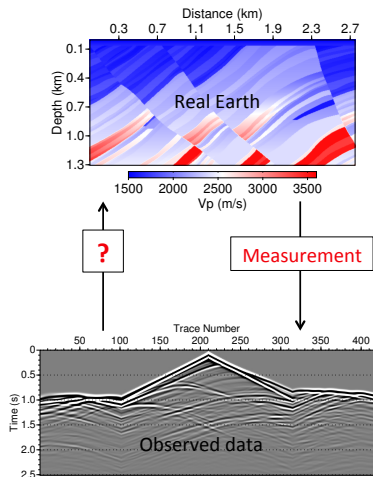
# Difficulties for Oil & Gas industry

- “Easy” reservoirs are already discovered
  - ▶ Improvement of the acquisition : number of channels and frequency band (Moore law)
  - ▶ Improvement of the imaging algorithms to handle complex geology (and high number of channels...)



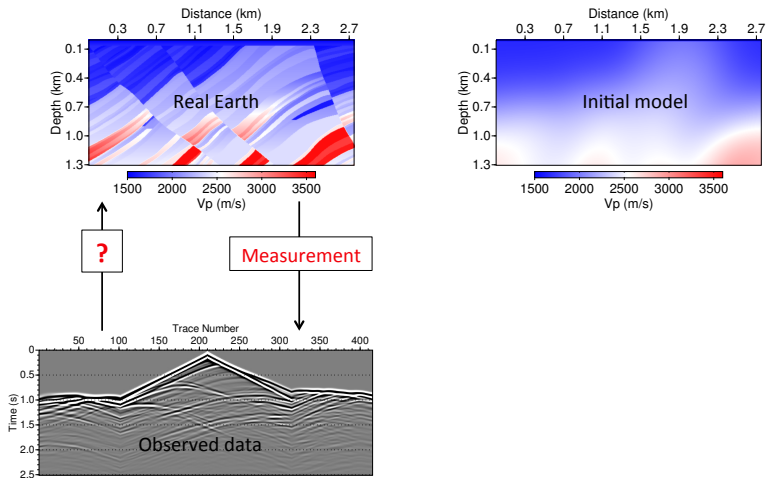
Keho & Kelamis, 2012

# Full waveform inversion : principle

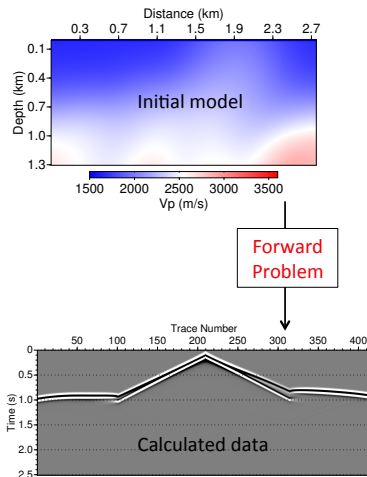
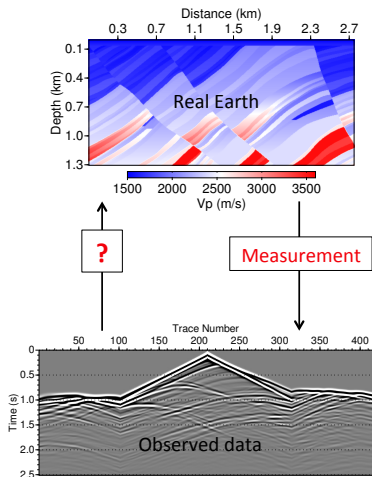




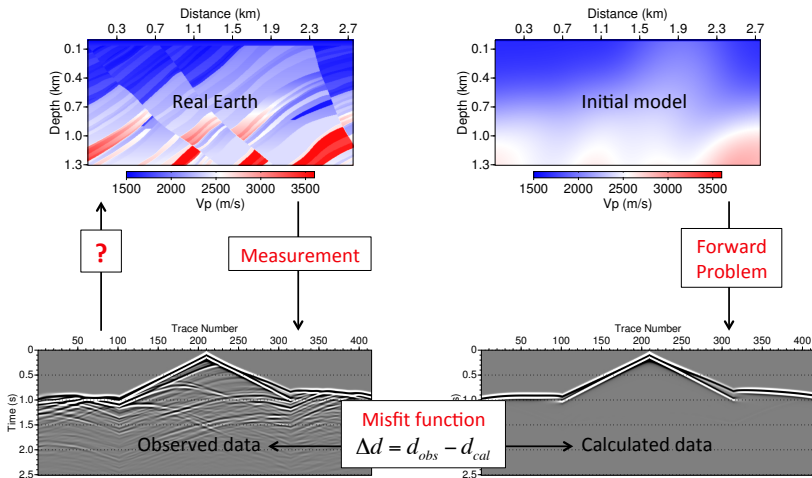
# Full waveform inversion : principle



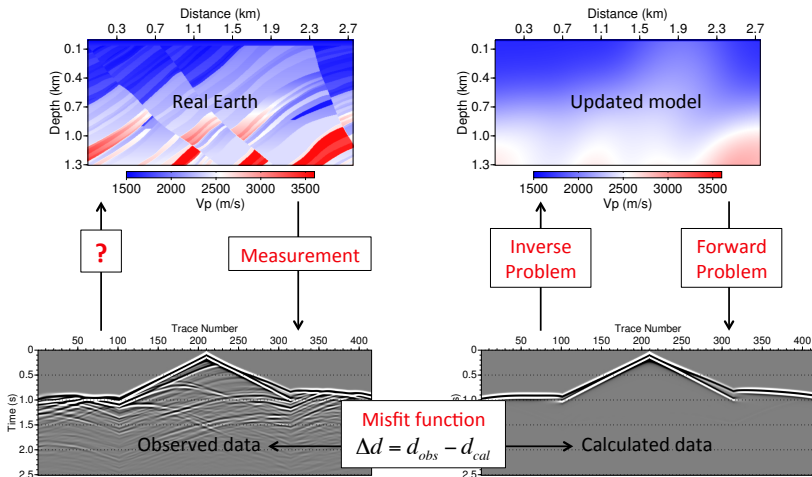
# Full waveform inversion : principle



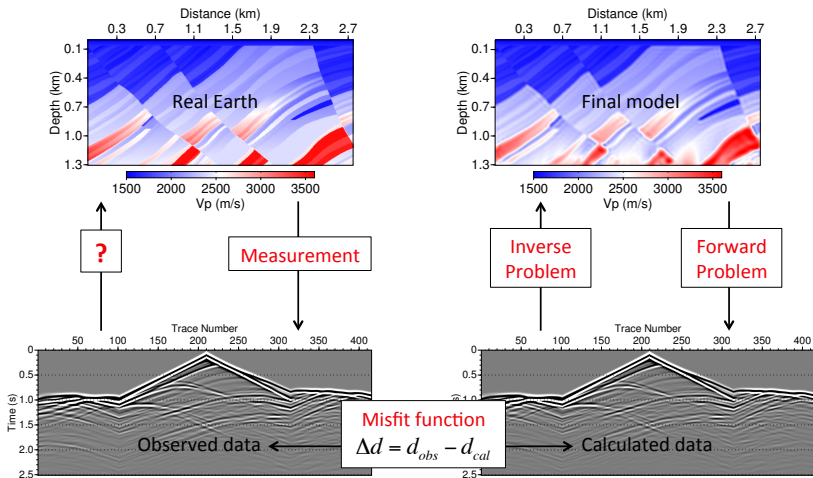
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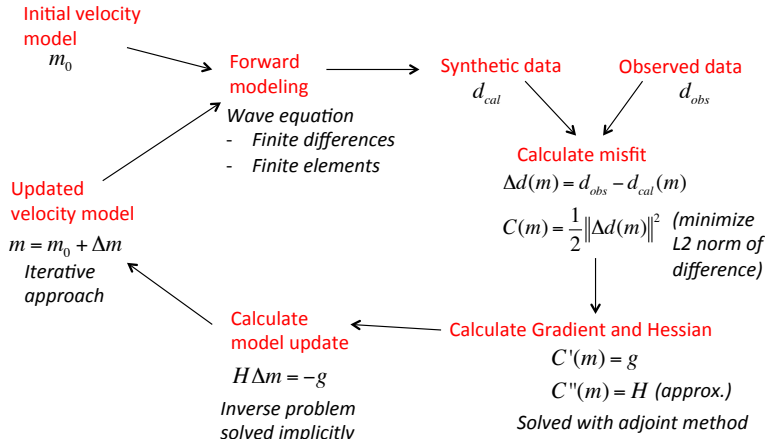
# Full waveform inversion : principle



# Full waveform inversion : principle



# Full waveform inversion : workflow



# Full waveform inversion : issues

FWI is a difficult problem that requires expertise in many fields

- Physics and Geophysics : understanding of physics of seismic waves
- Applied Mathematics : PDE, optimization and inverse problem
- Signal Processing
- HPC : efficient implementation of numerical method of modern HPC platforms and managing of large data volumes

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  - Frequency-domain PDE solver
  - Time-domain PDE solver
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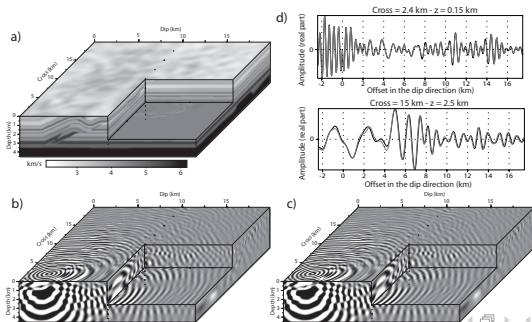
# Frequency-domain PDE solver

- Helmholtz equation for discretized with optimal finite-difference

$$\frac{\omega^2}{\kappa(\mathbf{x})} p(\mathbf{x}, \omega) + \frac{\partial}{\partial x} b(\mathbf{x}) \frac{\partial p(\mathbf{x}, \omega)}{\partial x} + \frac{\partial}{\partial y} b(\mathbf{x}) \frac{\partial p(\mathbf{x}, \omega)}{\partial y} + \frac{\partial}{\partial z} b(\mathbf{x}) \frac{\partial p(\mathbf{x}, \omega)}{\partial z} = s(\mathbf{x}, \omega) \quad (2)$$

- Leads to large sparse linear systems  $Ax = b$  with many ( $10^2 - 10^4$ ) RHS  
→ requires platforms with lots of core-memory

F (Hz)	h(m)	$n_u (10^6)$	$M_{LU} (Gb)$	$T_{LU} (s)$	$T_s (s)$	$N_p$
7	75	6.2	260	1822	0.97	64 (32*2)



# Outline

1 Introduction

2 Algorithm

- Frequency-domain PDE solver
- Time-domain PDE solver

3 Example on the Valhall Oil & Gas field

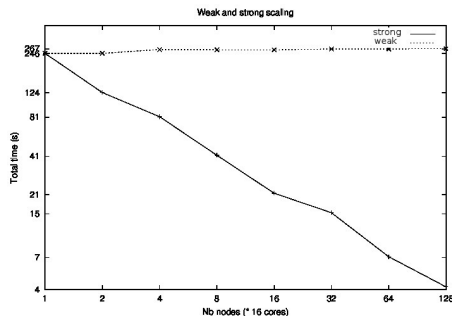
4 Perspectives and challenges on the HPC side

# Time-domain PDE solver

- Wave equation visco-acoustic media discretized with finite-difference

$$\frac{1}{\kappa(\mathbf{x})} \frac{\partial^2 p(\mathbf{x}, t)}{\partial t^2} + \frac{\partial}{\partial x} b(\mathbf{x}) \frac{\partial p(\mathbf{x}, t)}{\partial x} + \frac{\partial}{\partial y} b(\mathbf{x}) \frac{\partial p(\mathbf{x}, t)}{\partial y} + \frac{\partial}{\partial z} b(\mathbf{x}) \frac{\partial p(\mathbf{x}, t)}{\partial z} = s(\mathbf{x}, t) \quad (3)$$

- Explicit time-marching algorithms with high scalability  
→ number of cores is the crucial point

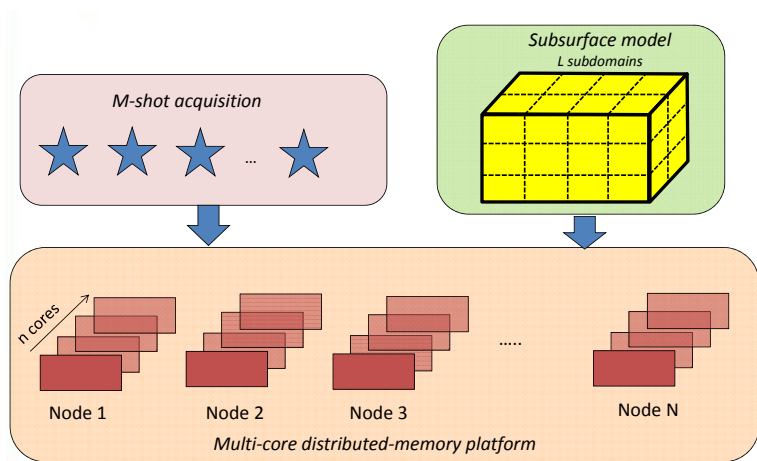


weak and strong scaling done on the Freeride slot on Froggy

- strong scaling : grid  
 $512 \times 1024 \times 1024$
- weak scaling :  
 $512 \times 1024 \times 1024$  points on 16 cores to  
 $2048 \times 4096 \times 4096$  points on 2048 cores

# Time-domain PDE solver

How to optimally distribute sources and computational mesh over MPI processes?  
2 levels of parallelism

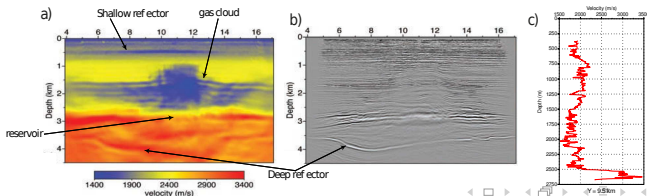
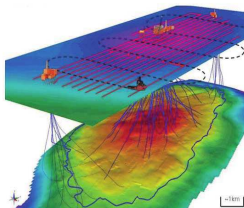
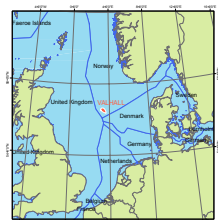


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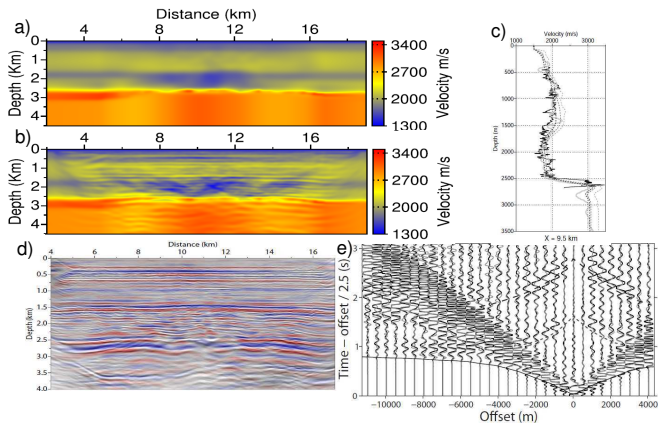
# The Valhall field environment and data

- Valhall field : off-shore shallow-water in the North Sea. Over-pressured, under-saturated, Upper Cretaceous chalk reservoir (exploited since 1982)
- Shale at shallow depth : strong inprint of anisotropy in the seismic data
- 3D seismic :  $\approx 50000$  shots, 2414 permanent 4C sensors on the sea bed (OBC)



# 2D Acoustic anisotropic inversion

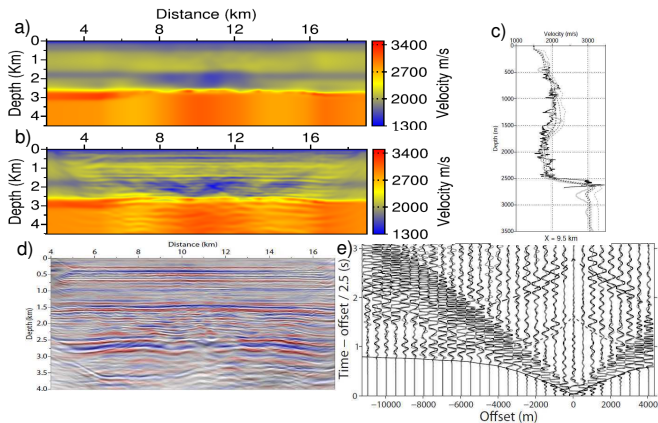
from Prioux et al, 2011, GJI





# 2D Acoustic anisotropic inversion

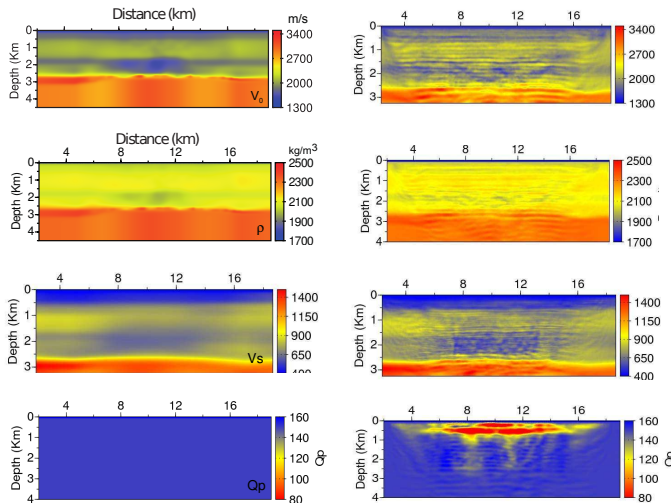
from Prioux et al, 2011, GJI



→ Jade/CINES, 52 h, 32 procs, 55 Gb of RAM

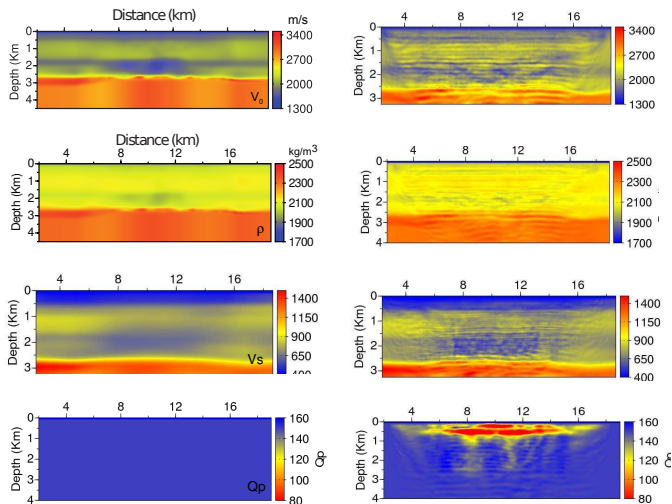
# 2D Elastic anisotropic inversion

from Prioux et al, 2013, GJI



# 2D Elastic anisotropic inversion

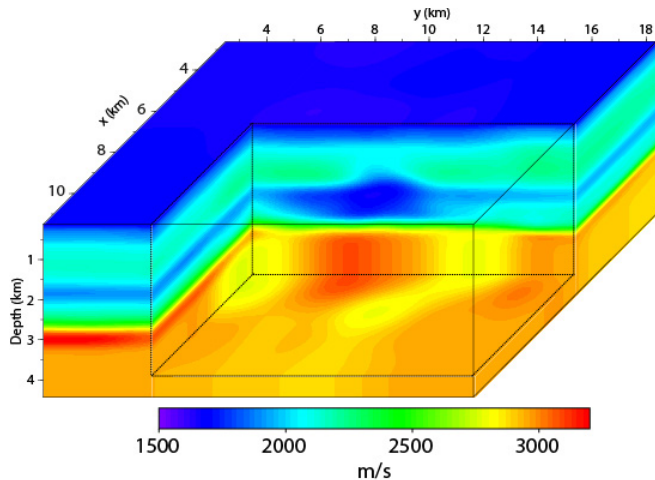
from Prioux et al, 2013, GJI



→ Jade/CINES. 42 h. 240 procs. 322 Go of RAM

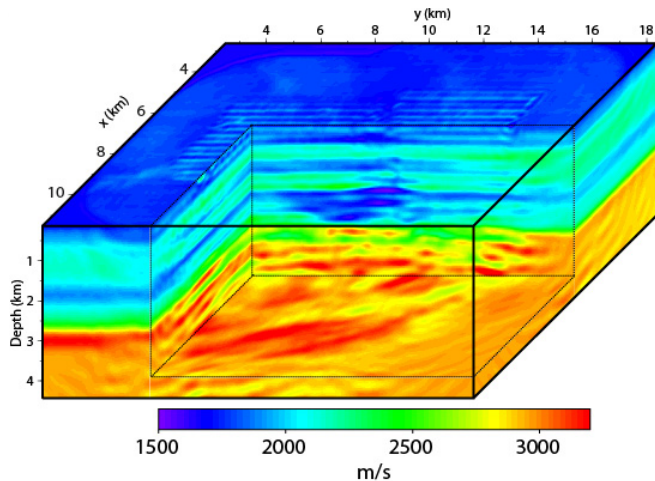
# 3D Acoustic inversion

Starting model from reflection tomography



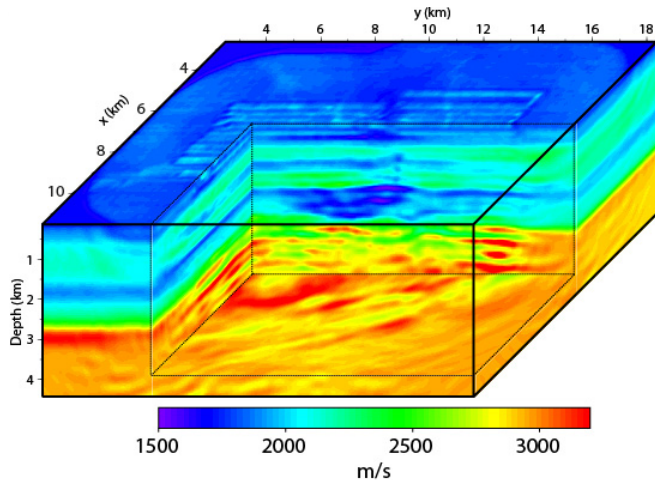
# 3D Acoustic inversion

FWI : [3.5,4] Hz



# 3D Acoustic inversion

FWI : [4,5] Hz



# 3D Acoustic inversion : Performances

Code	<i>TOY3DAC</i>	<i>GeoInv3D</i>
archi.	Gofree Intel cluster	IBM Blue Gene
nb cores	72	2048
time/it. (h)	1.33	2.30
tot. time/it. (h)	96	4710
theo. pic flop/it	3.1E15	5.8E16
tot memory	≈ 500Gb	≈ 500Gb

## ● Gofree Intel Cluster

- ▶ Intel Westmere nodes
- ▶ 2 proc. × 6 cores per node  
2.26 Ghz
- ▶ 72 Gb of memory per node
- ▶ Mellanox QDR 40 Gb/s  
Infiniband network

## ● IBM Blue Gene P (IDRIS) center

- ▶ Power PC 450 nodes
- ▶ 1 proc. × 4 cores per node  
850 MHz
- ▶ 2 Gb of memory per node

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# Perspectives and challenges on the HPC side

- Speed up : data “compression” and local optimization performances
- code efficiency : third parallelism level based on shared memory threads (OpenMP)
- Improve our physics : more complex PDE, but more expensive
- Tackle bigger problems
  - ▶ larger size targets :  $\approx 50 \times 50 \times 10$  km
  - ▶ higher frequencies :  $\approx 15$ -20 Hz
  - ▶ denser acquisition :  $\approx 10^5$  channels  $\times 10^4$  sources